

How mathematics helps unraveling the mystery behind somitogenesis

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Outline

- 1 Introduction
 - Somite Formation
 - Early Mathematical Models
 - Mathematical Model

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2 Theoretical Results

- Hopf Bifurcation Without Discrete Delay
- Hopf Bifurcation With Discrete Delay

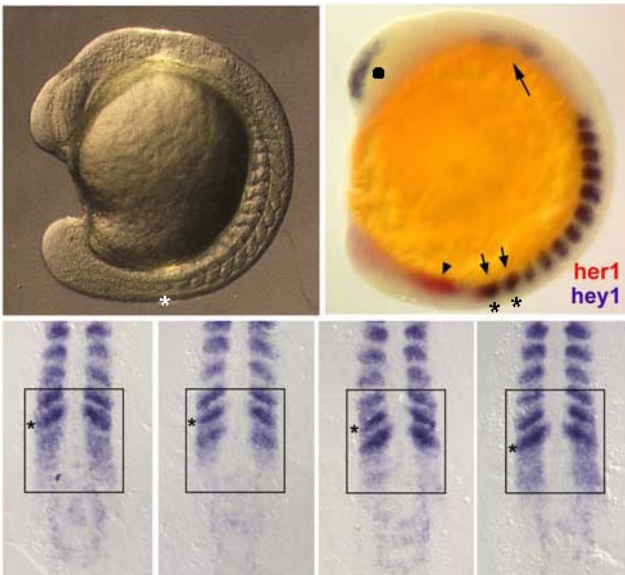
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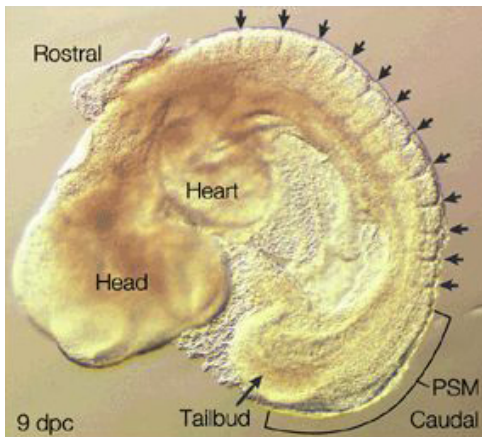
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- 3 Methods Applied
- 4 Numerical Simulations

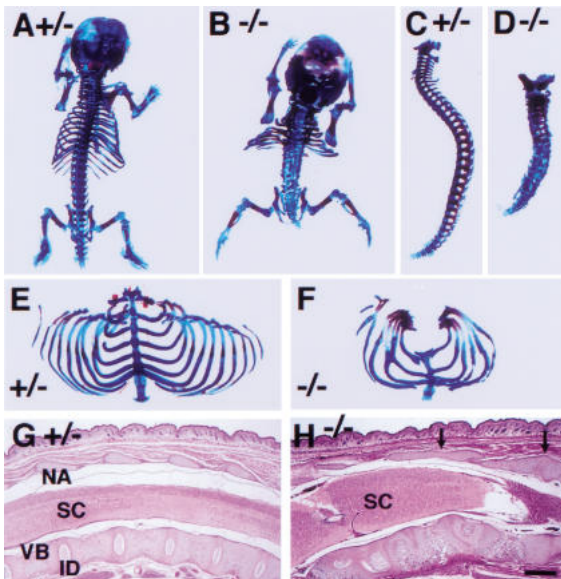
Somite Formation(Zebrafish Embryo)



Somite Formation(Mouse Embryo)



Laboratory Findings



Early Mathematical Models

- Clock and Wave-front Model, Cooke and Zeeman, 1976

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- Reaction Diffusion Model, Meinhardt, 1982
- Cell-cycle Model, Primmitt et al., 1989
- Molecular Clock Model, Palmeirim et al., 1997

Schematic Sketch of Gene Regulating Network

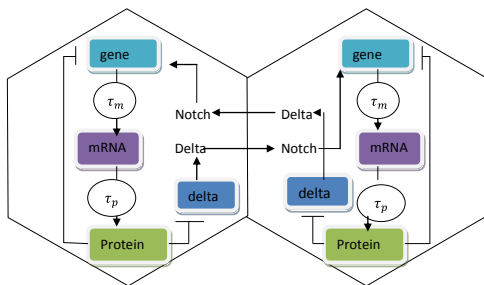


Figure: Schematic representation of communication among cells

A Simpler Diagram

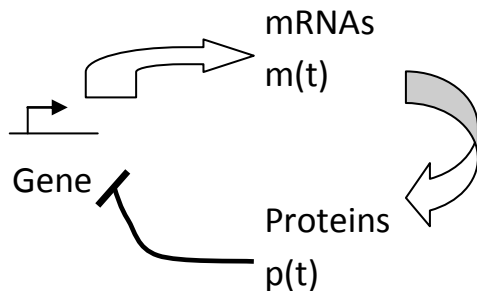


Figure: Schematic representation of gene regulation: Gene is transcribed into mRNA which is translated into protein. By binding to the promoter of the gene the protein represses further transcription of gene.

A Simple yet Illuminating Model

$$\begin{cases} \frac{dp}{dt} = am(t - \tau_p) - bp(t), \\ \frac{dm}{dt} = f(p(t - \tau_m)) - cm(t), \end{cases} \quad (1)$$

τ_p : the time lag between the initiation of the translation and the appearance of a mature protein

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$$f(p) = \frac{k\theta^n}{\theta^n + p^n},$$

is a sigmoid function which signifies the switch-like phenomena during the process.

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Assumptions of the Model

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- Movement of the protein between the cytoplasm and nucleus is neglected
- The delay takes a discrete, well-defined value

Steady States and Local Stability

Let $r = \tau_m / \tau_p$

Theorem

When $c > \frac{ka}{b\theta} \frac{n-1}{n} \sqrt{n-1}$, $E^* = (p^*, m^*)$ is asymptotically stable for all $r \geq 0$.
 When c is small, there exists a critical value r_0 such that the steady state E^* is asymptotically stable for $r \in [0, r_0)$ and unstable for $r > r_0$, where

$$r_0 = \frac{1}{\xi_+} \arccos \left\{ \frac{\xi_+^2 - bc\tau_p^2}{bc_1\tau_p^2} \right\} - 1, \quad (2)$$

and

$$\xi_+^2 = -\frac{1}{2}(b^2 + c^2)\tau_p^2 + \frac{1}{2}\tau_p^2[(b^2 - c^2)^2 + 4b^2c_1^2]^{1/2} \quad (3)$$

Lemma

Consider the equation

$$\lambda^2 + a\lambda + e + (c\lambda + d)e^{-\lambda r} = 0, \quad (4)$$

where a, b, c, d and e are real numbers. Let the hypotheses:

- (A1) $a + c > 0$,
- (A2) $e + d > 0$,
- (A3) $c^2 - a^2 + 2e < 0$ and $e^2 - d^2 > 0$ or $(c^2 - a^2 + 2e)^2 < 4(e^2 - d^2)$,
- (A4) $e^2 - d^2 < 0$ or $c^2 - a^2 + 2e > 0$ and $(c^2 - a^2 + 2e)^2 = 4(e^2 - d^2)$.

(a) if A1, A2 and A3 hold, then all roots of Eq.(4) have negative real parts for all $r \geq 0$.

(b) If A1, A2 and A4 hold, then there exists $r_0 > 0$ such that, when $r \in [0, r_0)$ all roots of (4) have negative real parts, when $r = r_0$, Eq.(4) has a pair of purely imaginary roots $\pm i\xi_+$, and for $r > r_0$ (4) has at least one root with positive real part. Here r_0 and ξ_+ are given by

Hopf Bifurcation

Theorem

When $c < \frac{ka}{b\theta} \frac{n-1}{n} \sqrt[n]{n-1}$, there exists $\epsilon_0 > 0$ such that for each $0 \leq \epsilon < \epsilon_0$, Eq.(1) have a family of periodic solutions $p_\epsilon(t)$ with period $T(\epsilon)$. Moreover, for the parameter $r = r(\epsilon)$, $p_0(t) = E^*$, $T(0) = \frac{2\pi}{\xi_+}$ and $r(0) = r_0$, where r_0 and ξ_+ are given in Eq.(2) and Eq.(3), respectively.

A More Realistic Mathematical Model

$$\begin{cases} \frac{dp}{dt} = am(t - \tau_p) - bp(t), \\ \frac{dm}{dt} = \int_{-\infty}^t g(t-s)f(p(s))ds - cm(t), \end{cases} \quad (5)$$

τ_p : time lag between the initiation of the translation and the appearance of a mature protein; b and c represent the degradation rates of proteins and mRNAs, respectively; a is the translation constant.

$$f(p) = \frac{k\theta^h}{\theta^h + p^h}, g(t) = \alpha e^{-\alpha t} (\text{Weak Kernel}), g(t) = \alpha^2 t e^{-\alpha t} (\text{Strong Kernel}).$$

Theoretical Results

Theorem (Weak Kernel Without Discrete Delay)

If (i) $bc < ad$ or

(ii) $bc > ad$, $(b + c)^2 + ad > 2(b + c)\sqrt{bc}$ and $\alpha > \alpha_0$ where α_0 is given by

$$\alpha_0 = \frac{ad - (b + c)^2 + \sqrt{\Delta}}{2(b + c)}, \text{ with } \Delta = [(b + c) - \sqrt{bc}]^2 - (bc - ad).$$

then the steady-state solution (p^*, m^*) is asymptotically stable.

If $bc > ad$, $(b + c)^2 + ad > 2(b + c)\sqrt{bc}$ and $\alpha \in [0, \alpha_0)$, then the steady state is unstable. Hopf bifurcation occurs when $\alpha = \alpha_0$.

Theoretical Results

Theorem (Strong Kernel Without Discrete Delay)

If $(2b + ad/b)^2 > 4b^2$, then (p^*, m^*) is locally asymptotically stable for $\alpha \in (0, \alpha_1) \cup (\alpha_2, +\infty)$ and is unstable for $\alpha \in (\alpha_1, \alpha_2)$. α_1, α_2 are given by

$$\alpha_1 = \frac{1}{2}[C_5 - \sqrt{C_5^2 - 4b^2}], \quad \alpha_2 = \frac{1}{2}[C_5 + \sqrt{C_5^2 - 4b^2}]$$

with $C_5 = (2b + ad/b)$. α_1 and α_2 are Hopf bifurcation values. If $(2b + ad/b)^2 < 4b^2$, then (p^*, m^*) is always asymptotically stable.

Theoretical Results

Theorem (Weak Kernel With Discrete Delay)

If $bc < -ad$, and ω_+ is the least simple root of equation (6),

$$\omega^6 + (A^2 - 2B)\omega^4 + (B^2 - 2AC)\omega^2 + C^2 - D^2 = 0 \quad (6)$$

then a Hopf bifurcation occurs as τ_p passes through

$$\tau_0 = \frac{1}{\omega_+} \arccos \left\{ \frac{A\omega_+^2 - C}{D} \right\}. \text{ Here}$$

$$A = b + c + \alpha, \quad C = \alpha bc, \quad D = -\alpha ad.$$

Theoretical Results

Theorem (Strong Kernel With Discrete Delay)

(i) If $B^2 - C^2 > 0$, $-A^2 + 2B < 0$ or $(-A^2 + 2B)^2 < 4(B^2 - C^2)$, then the steady state (p^, m^*) is asymptotically stable for all discrete delays;*

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- (ii) If $B^2 - C^2 < 0$ or $-A^2 + 2B > 0$, $(-A^2 + 2B)^2 = 4(B^2 - C^2)$, then the steady state is asymptotically stable for $\bar{\tau} \in [0, \min\{\tau_{0,1}^+, \tau_{0,1}^-\})$.
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(iii) If $B^2 - C^2 > 0$, $-A^2 + 2B > 0$, $(-A^2 + 2B)^2 > 4(B^2 - C^2)$, then the steady state is asymptotically stable for $\bar{\tau} \in [0, \min\{\tau_{0,1}^+, \tau_{0,1}^-\})$. When

$\bar{\tau} \in [\min\{\tau_{n,1}^+, \tau_{n,1}^-\}, \max\{\tau_{n,2}^+, \tau_{n,2}^-\}]$, the steady state is unstable, when

$\bar{\tau} \in [\max\{\tau_{n,2}^+, \tau_{n,2}^-\}, \min\{\tau_{n+1,2}^+, \tau_{n+1,2}^-\}]$, the steady state is stable.

Weak Kernel with Discrete Delay

Define

$$w(t) = \int_{-\infty}^t \alpha e^{-\alpha(t-s)} f(p(s)) ds.$$

The original system then becomes

$$\frac{dp}{dt} = am(t - \tau_p) - bp(t),$$

$$\frac{dm}{dt} = w(t) - cm(t),$$

$$\frac{dw}{dt} = \alpha(f(p(t)) - w(t)).$$

The linearized system takes the form:

$$\frac{dP}{dt} = aM(t - \tau_p) - bP(t),$$

$$\frac{dM}{dt} = W(t) - cM(t),$$

$$dW$$

Weak Kernel with Discrete Delay

Expanding this expression, we arrive at the following characteristic equation

$$\lambda^3 + A\lambda^2 + B\lambda + C + De^{-\tau_p\lambda} = 0,$$

where

$$A = b + c + \alpha, \quad B = \alpha(b + c) + bc, \quad C = \alpha bc, \quad D = -\alpha ad > 0.$$

Weak Kernel with Discrete Delay

Let $\lambda = \xi + i\omega$ be a solution to this quasi-polynomial characteristic equation. We can rewrite the equation in terms of the real and imaginary parts as

$$\begin{aligned}\xi^3 - 3\xi\omega + A\xi^2 - A\omega^2 + B\xi + C + De^{-\xi\tau_p} \cos(\omega\tau_p) &= 0 \\ 3\xi^2\omega - \omega^3 + 2A\xi\omega + B\omega - De^{-\xi\tau_p} \sin(\omega\tau_p) &= 0\end{aligned}$$

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Setting $\xi = 0$, we have

$$-A\omega^2 + C + D \cos(\xi\tau_p) = 0$$

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$$-A\omega^2 + C + D \cos(\xi\tau_p) = 0$$

$$-\omega^3 + B\omega - D \sin(\omega\tau_p) = 0$$

Thus

$$(-A\omega^2 + C)^2 + (-\omega^3 + B\omega)^2 = D^2.$$

Or equivalently,

$$\omega^6 + (A^2 - 2B)\omega^4 + (B^2 - 2AC)\omega^2 + C^2 - D^2 = 0 \quad (7)$$

Applying the next Lemma, we show that there is no real root to this equation when $C^2 - D^2 > 0$.

Lemma

The cubic equation

$$x^3 + a_1x^2 + a_2x + a_3 = 0$$

has at least one single positive root when $a_3 > 0$ if and only if

(1) Either $a_1 < 0$, $a_2 \geq 0$, $a_1^2 > 3a_2$ or $a_2 < 0$;

and

(2) $\frac{4}{27}a_2^3 - \frac{1}{27}a_1^2a_2^2 + \frac{4}{27}a_1^3a_3 - \frac{2}{3}a_1a_2a_3 + a_3^3 < 0$

Let ω_+ be the solution to (7). We denote

$$F(\lambda, \tau_p) = \lambda^3 + A\lambda^2 + B\lambda + C + De^{-\tau_p\lambda}. \quad (8)$$

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At $\tau_p = \tau_0$, $\lambda = i\omega_+$, it follows that

$$\frac{d}{d\tau_p} \operatorname{Re}(\lambda)|_{\tau_p=\tau_0} = \frac{\omega_+^2(3\omega_+^4 + 2(A^2 - 2B)\omega_+^2 + B^2 - 2AC)}{P^2 + Q^2}, \quad (9)$$

where

$$P = -3\omega_+^2 + B + \tau_0(-A\omega_+^2 + C),$$

and

$$Q = 2A\omega_+ + \tau_0(-\omega_+^3 + B\omega_+).$$

Linear Chain Trick

Let

$$w_2(t) = \int_{-\infty}^t \alpha^2(t-s)e^{-\alpha(t-s)}f(p(s))ds$$

and

$$w_1(t) = \int_{-\infty}^t \alpha e^{-\alpha(t-s)}f(p(s))ds,$$

we have the following equivalent system

$$\frac{dp}{dt} = am(t - \tau_p) - bp(t),$$

$$\frac{dm}{dt} = w_2(t) - cm(t),$$

$$\frac{dw_2}{dt} = \alpha(w_1(t) - w_2(t)),$$

$$\frac{dw_1}{dt} = \alpha(f(p(t)) - w_1(t)).$$

Characteristic Equation

The associated characteristic equation to the linearized system is

$$\begin{vmatrix} -b - \lambda & ae^{-\tau_p \lambda} & 0 & 0 \\ 0 & -c - \lambda & 1 & 0 \\ 0 & 0 & -\alpha - \lambda & \alpha \\ -\alpha d & 0 & 0 & -\alpha - \lambda \end{vmatrix} = 0.$$

Expansion of the above equation yields

$$(b + \lambda)(c + \lambda)(\alpha + \lambda)^2 + \alpha^2 ade^{-\tau_p \lambda} = 0.$$

Simplification

Assuming $b = c$, the characteristic equation then becomes

$$(b + \lambda)(\alpha + \lambda) = \pm \alpha \sqrt{ad} e^{-\lambda \tau_p / 2}.$$

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$$A = b + \alpha, \quad B = b\alpha, \quad C = \alpha \sqrt{ad}, \quad \bar{\tau} = \tau_p / 2.$$

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The characteristic equation then takes the following form

$$\lambda^2 + A\lambda + B \pm C e^{-\bar{\tau}\lambda} = 0.$$

Analysis of the Roots

Let

$$\xi_+ = \sqrt{\frac{1}{2}(-A^2 + 2B) + [1/4(-A^2 + B)^2 - (B^2 - C^2)]^{1/2}},$$

and

$$\tau_{n,1}^+ = \frac{1}{\xi_+} \arcsin\left(\frac{\xi_+^2 - B}{C}\right) + \frac{2n\pi}{\xi_+}.$$

Let

$$\xi_- = \sqrt{\frac{1}{2}(-A^2 + 2B) - [1/4(-A^2 + B)^2 - (B^2 - C^2)]^{1/2}},$$

and

$$\tau_{n,2}^+ = \frac{1}{\xi_-} \arcsin\left(\frac{\xi_-^2 - B}{C}\right) + \frac{2n\pi}{\xi_-}.$$

Analysis of the Roots

Let

$$\eta_+ = \sqrt{\frac{1}{2}(-A^2 + 2B) + [1/4(-A^2 + B)^2 - (B^2 - C^2)]^{1/2}},$$

and

$$\bar{\tau} = \tau_{n,1}^- = -\frac{1}{\eta_+} \arcsin\left(\frac{\eta_+^2 - B}{C}\right) + \frac{2n\pi}{\eta_+}.$$

Let

$$\eta_- = \sqrt{\frac{1}{2}(-A^2 + 2B) - [1/4(-A^2 + B)^2 - (B^2 - C^2)]^{1/2}},$$

and

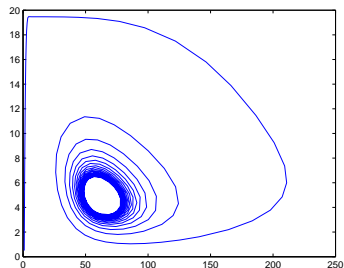
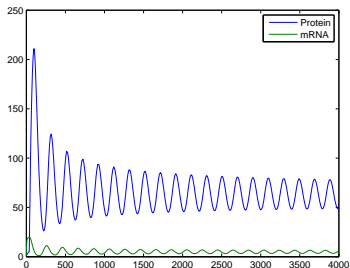
$$\tau_{n,2}^- = -\frac{1}{\eta_-} \arcsin\left(\frac{\eta_-^2 - B}{C}\right) + \frac{2n\pi}{\eta_-}.$$

Parameters

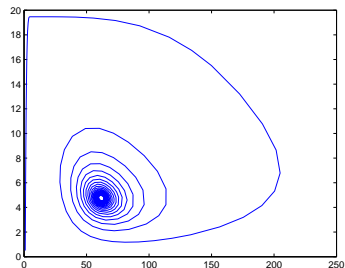
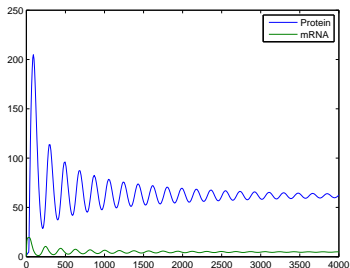
Table: Estimated parameters for *hes7* gene.

Parameter	Value	Description
a	0.45 molecules/min	translation constant
b	0.0347 or 0.0231 molecules/min	0.0347 for wild-type and 0.0231 for Hes7K14R
c	0.231 molecules/min	mRNA degradation rate
k	4.5 molecules/cell·min	critical protein concentration
h	2.6	Hill coefficient
θ	40 molecules	DNA dissociation constant
τ_p	20-40 min	Translation delay
α	controlled	

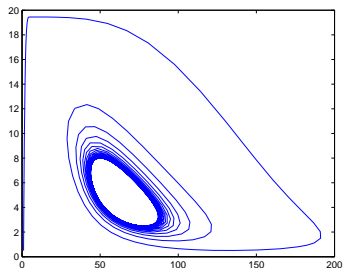
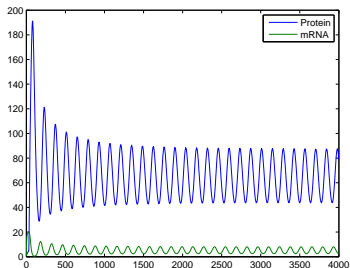
Sustained Oscillation $\tau_p = 35, \alpha = 2/40$



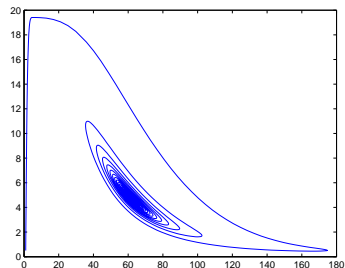
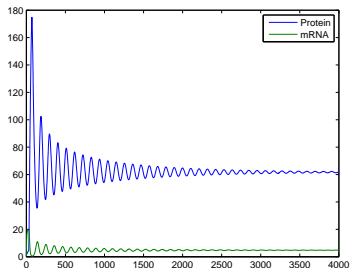
Damped Oscillation $\tau_p = 30, \alpha = 2/40$



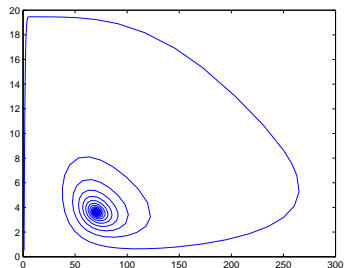
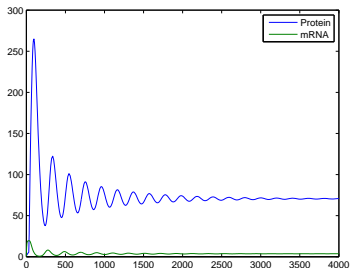
Sustained Oscillation for Large Distributed Delay $\tau_p = 30, \alpha = 2/15$



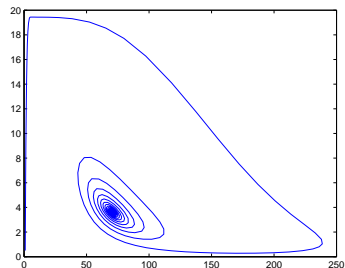
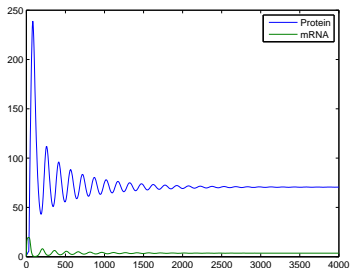
Stability Switch When α Increases $\tau_p = 30, \alpha = 2$



Damped Oscillation for mutant Hes7K14R $\tau_p = 35$, $\alpha = 2/40$, $b \approx 0.0231$



Damping oscillation for mutant Hes7K14R $\tau_p = 30, \alpha = 2/15, b \approx 0.0231$



Future Directions

- Explore the role of Delta-Notch pathway;

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- Numerically simulate synchronization among multiple cells;

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- Explore the role of Delta-Notch pathway;
- Numerically simulate synchronization among multiple cells;
- Consider the effect of diffusion of cells during early stage of embryos.

References:

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